



THE SEAL APPEARING ON THIS DOCUMENT
WAS AUTHORIZED BY
GABRIEL R. GARCIA, PE #125068 ON 07/28/2026

MECHANICAL ITEMS FOR ADDENDUM NO. 3

NOTICE TO PROPOSERS:

- A. This Addendum shall be considered part of the contract documents for the above-mentioned project as though it had been issued at the same time and incorporated integrally therewith. Where provisions of the following supplementary data differ from those of the original contract documents, this Addendum shall govern and take precedence.
- B. Proposers are hereby notified that they shall make any necessary adjustments in their estimate on account of this Addendum. It will be construed that each Proposer's proposal is submitted with full knowledge of all modifications and supplemental data specified therein. Acknowledge receipt of this addendum in the space provided on the proposal form. Failure to do so may subject Proposer to disqualification.

REFERENCE IS MADE TO THE DRAWINGS AND THE PROJECT MANUAL AS NOTED:

PROJECT MANUAL:

AD No 3, Mech. Item 1: To the Project Manual, Section 23 0923, "DIRECT-DIGITAL CONTROL SYSTEM FOR HVAC"

Remove Section 2.01.A. To provide clarity from pre-bid RFIs, there are no Alternate 3 items to be included. Base Bid cost shall be to provide new Carrier i-Vu controls for new mechanical equipment as an extension of the existing campus building automation system.

END OF MECHANICAL ADDENDUM

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SECTION 23 0923
DIRECT-DIGITAL CONTROL SYSTEM FOR HVAC

PART 1 GENERAL

1.01 SECTION INCLUDES

- A. System description.
- B. Operator interface.
- C. Controllers.
- D. Power supplies and line filtering.
- E. Controller software.
- F. HVAC control programs.



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1.02 RELATED REQUIREMENTS

- A. Section 23 0913 - Instrumentation and Control Devices for HVAC.
- B. Section 23 0993 - Sequence of Operations for HVAC Controls.
- C. Section 26 0583 - Wiring Connections: Electrical characteristics and wiring connections.

1.03 REFERENCE STANDARDS

- A. ASHRAE Std 135 - A Data Communication Protocol for Building Automation and Control Networks; 2020, with Errata (2023).
- B. MIL-STD-810 - Environmental Engineering Considerations and Laboratory Tests; 2019h.

1.04 SUBMITTALS

- A. See Section 01 3000 - Administrative Requirements for submittal procedures.
- B. Product Data: Provide data for each system component and software module.
- C. Shop Drawings:
 - 1. Indicate trunk cable schematic showing programmable control unit locations, and trunk data conductors.
 - 2. List connected data points, including connected control unit and input device.
 - 3. Indicate system graphics indicating monitored systems, data (connected and calculated) point addresses, and operator notations. Provide demonstration digital media containing graphics.
 - 4. Show system configuration with peripheral devices, batteries, power supplies, diagrams, modems, and interconnections.
 - 5. Indicate description and sequence of operation of operating, user, and application software.
- D. Project Record Documents: Record actual locations of control components, including control units, thermostats, and sensors.
 - 1. Revise shop drawings to reflect actual installation and operating sequences.
 - 2. Include submittals data in final "Record Documents" form.
- E. Operation and Maintenance Data:
 - 1. Include interconnection wiring diagrams complete field installed systems with identified and numbered, system components and devices.
 - 2. Include keyboard illustrations and step-by-step procedures indexed for each operator function.
 - 3. Include inspection period, cleaning methods, cleaning materials recommended, and calibration tolerances.
- F. Warranty: Submit manufacturer's warranty and ensure forms have been filled out in Owner's name and registered with manufacturer.

1.05 QUALITY ASSURANCE

- A. Manufacturer Qualifications: Company specializing in manufacturing products specified in this section with minimum three years of documented experience.
- B. Installer Qualifications: Company specializing in performing work of the type specified and with minimum three years of documented experience.

1.06 WARRANTY

- A. See Section 01 7800 - Closeout Submittals for additional warranty requirements.
- B. Correct defective Work within a five year period after Substantial Completion.
- C. Provide five year manufacturer's warranty for field programmable micro-processor based units.

PART 2 PRODUCTS

2.01 BIDDING

- A. Not Used.

2.02 MANUFACTURERS

- A. Carrier i-Vu.

2.03 SYSTEM DESCRIPTION

- A. Automatic temperature control field monitoring and control system using field programmable micro-processor based units with communications to Building Management System specified in Section 23 09 23.
- B. Base system on distributed system of fully intelligent, stand-alone controllers, operating in a multi-tasking, multi-user environment on token passing network, with central and remote hardware, software, and interconnecting wire and conduit.
- C. Include computer software and hardware, operator input/output devices, control units, local area networks (LAN), sensors, control devices, actuators.
- D. Controls for variable air volume terminals, radiation, reheat coils, unit heaters, fan coils, and the like when directly connected to the control units. Individual terminal unit control is specified in Section 23 0913.
- E. Provide control systems consisting of thermostats, control valves, dampers and operators, indicating devices, interface equipment and other apparatus and accessories required to operate mechanical systems, and to perform functions specified.
- F. Include installation and calibration, supervision, adjustments, and fine tuning necessary for complete and fully operational system.

2.04 OPERATOR INTERFACE

- A. PC Based Work Station:
 - 1. Resides on high speed network with building controllers.
 - 2. Connected to server for full access to all system information.
- B. Workstation, controllers, and control backbone to communicate using BACnet protocol and addressing.
- C. BACnet protocol to comply with ASHRAE Std 135.

2.05 CONTROLLERS

- A. Building Controllers:
 - 1. General:
 - a. Manage global strategies by one or more, independent, standalone, microprocessor based controllers.
 - b. Provide sufficient memory to support controller's operating system, database, and programming requirements.
 - c. Share data between networked controllers.

- d. Controller operating system manages input and output communication signals allowing distributed controllers to share real and virtual object information and allowing for central monitoring and alarms.
 - e. Utilize real-time clock for scheduling.
 - f. Continuously check processor status and memory circuits for abnormal operation.
 - g. Controller to assume predetermined failure mode and generate alarm notification upon detection of abnormal operation.
 - h. Communication with other network devices to be based on assigned protocol.
 - 2. Communication:
 - a. Controller to reside on a BACnet network using ISO 8802-3 (ETHERNET) Data Link/Physical layer protocol.
 - b. Perform routing when connected to a network of custom application and application specific controllers.
 - c. Provide service communication port for connection to a portable operator's terminal or hand held device with compatible protocol.
 - 3. Anticipated Environmental Ambient Conditions:
 - a. Outdoors and/or in Wet Ambient Conditions:
 - 1) Mount within waterproof enclosures.
 - b. Conditioned Space:
 - 1) Mount within dustproof enclosures.
 - 4. Provisions for Serviceability:
 - a. Diagnostic LEDs for power, communication, and processor.
 - b. Make all wiring connections to field removable, modular terminal strips, or to a termination card connected by a ribbon cable.
 - 5. Memory: In the event of a power loss, maintain all BIOS and programming information for a minimum of 72 hours.
 - 6. Power and Noise Immunity:
 - a. Maintain operation at 90 to 110 percent of nominal voltage rating.
 - b. Perform orderly shutdown below 80 percent of nominal voltage.
 - c. Operation protected against electrical noise of 5 to 120 Hz and from keyed radios up to 5 W. at 3 feet.
- B. Custom Application Controller:
- 1. General:
 - a. Provide sufficient memory to support controller's operating system, database, and programming requirements.
 - b. Share data between networked, microprocessor based controllers.
 - c. Controller operating system manages input and output communication signals allowing distributed controllers to share real and virtual object information and allowing for central monitoring and alarms.
 - d. Utilize real-time clock for scheduling.
 - e. Continuously check processor status and memory circuits for abnormal operation.
 - f. Controller to assume predetermined failure mode and generate alarm notification upon detection of abnormal operation.
 - g. Communication with other network devices to be based on assigned protocol.
 - 2. Communication:
 - a. Controller to reside on a BACnet network using MS/TP Data Link/Physical layer protocol.
 - b. Provide service communication port for connection to a portable operator's terminal or hand held device with compatible protocol.
 - 3. Anticipated Environmental Ambient Conditions:
 - a. Outdoors and/or in Wet Ambient Conditions:
 - 1) Mount within waterproof enclosures.
 - b. Conditioned Space:

- 1) Mount within dustproof enclosures.
4. Provisions for Serviceability:
 - a. Diagnostic LED's for power, communication, and processor.
 - b. Make all wiring connections to field removable, modular terminal strips, or to a termination card connected by a ribbon cable.
5. Memory: In the event of a power loss, maintain all BIOS and programming information for a minimum of 72 hours.
6. Power and Noise Immunity:
 - a. Maintain operation at 90 to 110 percent of nominal voltage rating.
 - b. Perform orderly shutdown below 80 percent of nominal voltage.
 - c. Operation protected against electrical noise of 5 to 120 Hz and from keyed radios up to 5 W. at 3 feet.
- C. Application Specific Controllers:
 1. General:
 - a. Not fully user programmable, microprocessor based controllers dedicated to control specific equipment.
 - b. Customized for operation within the confines of equipment served.
 - c. Communication with other network devices to be based on assigned protocol.
 2. Communication:
 - a. Controller to reside on a BACnet network using MS/TP Data Link/Physical layer protocol.
 - b. Provide service communication port for connection to a portable operator's terminal or hand held device with compatible protocol.
 3. Anticipated Environmental Ambient Conditions:
 - a. Outdoors and/or in Wet Ambient Conditions:
 - 1) Mount within waterproof enclosures.
 - b. Conditioned Space:
 - 1) Mount within dustproof enclosures.
 4. Provisions for Serviceability:
 - a. Diagnostic LEDs for power, communication, and processor.
 - b. Make all wiring connections to field removable, modular terminal strips, or to a termination card connected by a ribbon cable.
 5. Memory: In the event of a power loss, maintain all BIOS and programming information for a minimum of 72 hours.
 6. Power and Noise Immunity:
 - a. Maintain operation at 90 to 110 percent of nominal voltage rating.
 - b. Perform orderly shutdown below 80 percent of nominal voltage.
 - c. Operation protected against electrical noise of 5 to 120 Hz and from keyed radios up to 5 W at 3 feet.
- D. Input/Output Interface:
 1. Hardwired inputs and outputs tie into the DDC system through building, custom application, or application specific controllers.
 2. All Input/Output Points:
 - a. Protect controller from damage resulting from any point short-circuiting or grounding and from voltage up to 24 volts of any duration.
 - b. Provide universal type for building and custom application controllers where input or output is software designated as either binary or analog type with appropriate properties.
 3. Binary Inputs:
 - a. Allow monitoring of On/Off signals from remote devices.
 - b. Provide wetting current of 12 mA minimum, compatible with commonly available control devices and protected against the effects of contact bounce and noise.
 - c. Sense dry contact closure with power provided only by the controller.

4. Pulse Accumulation Input Objects: Comply with all requirements of binary input objects and accept up to 10 pulses per second.
5. Analog Inputs:
 - a. Allow for monitoring of low voltage 0 to 10 VDC, 4 to 20 mA current, or resistance signals (thermistor, RTD).
 - b. Compatible with and field configurable to commonly available sensing devices.
6. Binary Outputs:
 - a. Used for On/Off operation or a pulsed low-voltage signal for pulse width modulation control.
 - b. Outputs provided with three position (On/Off/Auto) override switches.
 - c. Status lights for building and custom application controllers to be selectable for normally open or normally closed operation.
7. Analog Outputs:
 - a. Monitoring signal provides a 0 to 10 VDC or a 4 to 20 mA output signal for end device control.
 - b. Provide status lights and two position (AUTO/MANUAL) switch for building and custom application controllers with manually adjustable potentiometer for manual override on building and custom application controllers.
 - c. Drift to not exceed 0.4 percent of range per year.
8. Tri State Outputs:
 - a. Coordinate two binary outputs to control three point, floating type, electronic actuators without feedback.
 - b. Limit the use of three point, floating devices to the following zone and terminal unit control applications:
 - 1) VAV terminal units.
 - c. Control algorithms run the zone actuator to one end of its stroke once every 24 hours for verification of operator tracking.
9. System Object Capacity:
 - a. System size to be expandable to twice the number of input output objects required by providing additional controllers, including associated devices and wiring.
 - b. Hardware additions or software revisions for the installed operator interfaces are not to be required for future, system expansions.

2.06 POWER SUPPLIES AND LINE FILTERING

- A. Power Supplies:
 1. Provide UL listed control transformers with Class 2 current limiting type or over-current protection in both primary and secondary circuits for Class 2 service as required by the NEC.
 2. Limit connected loads to 80 percent of rated capacity.
 3. Match DC power supply to current output and voltage requirements.
 4. Unit to be full wave rectifier type with output ripple of 5.0 mV maximum peak to peak.
 5. Regulation to be 1 percent combined line and load with 100 microsecond response time for 50 percent load changes.
 6. Provide over-voltage and over-current protection to withstand a 150 percent current overload for 3 seconds minimum without trip-out or failure.
 7. Operational Ambient Conditions: 32 to 120 degrees F.
 8. EM/RF meets FCC Class B and VDE 0871 for Class B and MIL-STD-810 for shock and vibration.
 9. Line voltage units UL recognized and CSA approved.
- B. Power Line Filtering:
 1. Provide external or internal transient voltage and surge suppression component for all workstations and controllers.
 2. Minimum surge protection attributes:

- a. Dielectric strength of 1000 volts minimum.
- b. Response time of 10 nanoseconds or less.
- c. Transverse mode noise attenuation of 65 dB or greater.
- d. Common mode noise attenuation of 150 dB or greater at 40 to 100 Hz.

2.07 CONTROLLER SOFTWARE

- A. All applications reside and operate in the system controllers and editing of all applications occurs at the operator workstation.
- B. System Security:
 1. User access secured via user passwords and user names.
 2. Passwords restrict user to the objects, applications, and system functions as assigned by the system manager.
 3. User Log On/Log Off attempts are recorded.
 4. Automatic Log Off occurs following the last keystroke after a user defined delay time.
- C. Object or Object Group Scheduling:
 1. Weekly Schedules Based on Separate, Daily Schedules:
 - a. Include start, stop, optimal stop, and night economizer.
 - b. 10 events maximum per schedule.
 - c. Start/stop times adjustable for each group object.
- D. Provide standard application for equipment coordination and grouping based on function and location to be used for scheduling and other applications.
- E. Alarms:
 1. Binary object is set to alarm based on the operator specified state.
 2. Analog object to have high/low alarm limits.
 3. All alarming is capable of being automatically and manually disabled.
 4. Alarm Reporting:
 - a. Operator determines action to be taken for alarm event.
 - b. Alarms to be routed to appropriate workstation.
 - c. Reporting Options:
- F. Maintenance Management: System monitors equipment status and generates maintenance messages based upon user-designated run-time limits.
- G. Sequencing: Application software based upon specified sequences of operation in Section 23 0993.
- H. PID Control Characteristics:
 1. Direct or reverse action.
 2. Anti-windup.
 3. Calculated, time-varying, analog value, positions an output or stages a series of outputs.
 4. User selectable controlled variable, set-point, and PED gains.
- I. Staggered Start Application:
 1. Prevents all controlled equipment from simultaneously restarting after power outage.
 2. Order of equipment startup is user selectable.
- J. Energy Calculations:
 1. Accumulated instantaneous power or flow rates are converted to energy use data.
 2. Algorithm calculates a rolling average and allows window of time to be user specified in minute intervals.
 3. Algorithm calculates a fixed window average with a digital input signal from a utility meter defining the start of the window period that in turn synchronizes the fixed-window average with that used by the power company.
- K. Anti-Short Cycling:
 1. All binary output objects protected from short-cycling.

2. Allows minimum on-time and off-time to be selected.
- L. On-Off Control with Differential:
 1. Algorithm allows binary output to be cycled based on a controlled variable and set-point.
 2. Algorithm to be direct-acting or reverse-acting incorporating an adjustable differential.
- M. Run-Time Totalization:
 1. Totalize run-times for all binary input objects.
 2. Provides operator with capability to assign high run-time alarm.

2.08 HVAC CONTROL PROGRAMS

- A. General:
 1. Support Inch-pounds and SI (metric) units of measurement.
 2. Identify each HVAC Control system.
- B. Optimal Run Time:
 1. Control start-up and shutdown times of HVAC equipment for both heating and cooling.
 2. Base on occupancy schedules, outside air temperature, seasonal requirements, and interior room mass temperature.
 3. Start-up systems by using outside air temperature, room mass temperatures, and adaptive model prediction for how long building takes to warm up or cool down under different conditions.
 4. Use outside air temperature to determine early shut down with ventilation override.
 5. Analyze multiple building mass sensors to determine seasonal mode and worse case condition for each day.
- C. Supply Air Reset:
 1. Monitor heating and cooling loads in building spaces, terminal reheat systems, both hot deck and cold deck temperatures on dual duct and multizone systems, single zone unit discharge temperatures.
 2. Adjust discharge temperatures to most energy efficient levels satisfying measured load by:
 - a. Raising cooling temperatures to highest possible value.
 - b. Reducing heating temperatures to lowest possible level.
- D. Enthalpy Switchover:
 1. Calculate outside and return air enthalpy using measured temperature and relative humidity; determine energy expended and control outside and return air dampers.

2.09 CHILLER CONTROL PROGRAMS

- A. Control function of condenser water reset, chilled water reset, and chiller sequencing. Support inch-pounds and SI (metric) units of measurement.
- B. Condenser Water Reset: Automatically reset controlled condenser water temperature using measured outside wet bulb temperature and load being handled.
- C. Chilled Water Reset: Automatically reset controlled chilled water temperature satisfying cooling coil requiring greatest cooling.
- D. Chiller Sequencing: Determine which combination of chillers will most efficiently satisfy chilled water load, by cycling chillers, based on comparing load to switchover limits defined for each chiller.

PART 3 EXECUTION

3.01 EXAMINATION

- A. Verify existing conditions before starting work.
- B. Verify that conditioned power supply is available to the control units and to the operator work station. Verify that field end devices, wiring, and pneumatic tubing is installed prior to installation proceeding.

3.02 INSTALLATION

- A. Install control units and other hardware in position on permanent walls where not subject to excessive vibration.
- B. Install software in control units and in operator work station. Implement all features of programs to specified requirements and appropriate to sequence of operation. Refer to Section 23 0993.
- C. Provide conduit and electrical wiring in accordance with Section 26 0583. Electrical material and installation shall be in accordance with appropriate requirements of Division 26.

3.03 MANUFACTURER'S FIELD SERVICES

- A. Start and commission systems. Allow sufficient time for start-up and commissioning prior to placing control systems in permanent operation.
- B. Provide service engineer to instruct Owner's representative in operation of systems plant and equipment for 3 day period.

3.04 DEMONSTRATION AND INSTRUCTIONS

- A. Demonstrate complete and operating system to Owner.

END OF SECTION